

```
// Alcuin Montessori School
// Adolescent Program
// Air Morse
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```

```
#include <LiquidCrystal.h>
```

```
// ----- Team Display -----
//
```

```
// LED functions:
```

```
// Green light is IO 9
// Red 1 (next to green light) is IO 8
// Red 2 is IO 7
// Red 3 is IO 6
```

```
#define GREEN 9
#define RED1 8
#define RED2 7
#define RED3 6
```

```
void displayDih()
{
  digitalWrite(GREEN, HIGH) ;
  digitalWrite(RED1, LOW ) ;
  digitalWrite(RED2, HIGH) ;
  digitalWrite(RED3, LOW ) ;
}
```

```
void displayDah()
{
  digitalWrite(GREEN, HIGH) ;
  digitalWrite(RED1, HIGH) ;
  digitalWrite(RED2, HIGH) ;
  digitalWrite(RED3, HIGH) ;
}
```

```
void displaySpace()
{
  digitalWrite(GREEN, HIGH) ;
  digitalWrite(RED1, LOW ) ;
  digitalWrite(RED2, LOW ) ;
  digitalWrite(RED3, LOW ) ;
}
```

```
void displayClear()
{
  digitalWrite(GREEN, LOW) ;
  digitalWrite(RED1, LOW) ;
  digitalWrite(RED2, LOW) ;
  digitalWrite(RED3, LOW) ;
}
```

```
// LCD functions:
```

```
LiquidCrystal lcd (12, 11, 5, 4, 3, 2);
```

```
int row = 0 ;
int col = 0 ;
```

```
void displayChar(char c)
{
  int i ;

  if(c==8)
```

```

    return displayBackspace() ;

col = col + 1 ;
if(col>15)
{
  col = 0 ;
  row = row + 1 ;
  if(row>1)
    row = 0 ;
  for(i=0 ; i<16 ; i++)
  {
    lcd.setCursor(i,row) ;
    lcd.print(" ") ;
  }
}
lcd.setCursor(col,row) ;
lcd.print(c) ;
}

void displayBackspace()
{
  lcd.setCursor(col,row) ;
  lcd.print(' ') ;

  col = col - 1;
  if(col<0)
  {
    col = 15 ;
    row = row -1 ;
    if(row<0)
      row = 1 ;
  }
  lcd.setCursor(col,row) ;
}

// Initialize function:

void displayInit()
{
  // set LED pin directions
  pinMode (GREEN, OUTPUT) ;
  pinMode (RED1, OUTPUT) ;
  pinMode (RED2, OUTPUT) ;
  pinMode (RED3, OUTPUT) ;

  // start LEDs off
  displayClear() ;

  // setup LCD display
  lcd.begin(16, 2);
  lcd.cursor() ;
  lcd.clear() ;
  lcd.print("AMSAP Air Morse");
  row = 1 ;
  col = 0 ;
}

// ----- Team Decode -----
//

char decode(char morse[])
{
  if(0==strcmp(morse, ".-" )) return 'A' ;
  if(0==strcmp(morse, "-..." )) return 'B' ;
  if(0==strcmp(morse, "-.-." )) return 'C' ;
  if(0==strcmp(morse, "-.." )) return 'D' ;
  if(0==strcmp(morse, "." )) return 'E' ;
}

```

```

if(0==strcmp(morse, "...-." )) return 'F' ;
if(0==strcmp(morse, "-.-." )) return 'G' ;
if(0==strcmp(morse, ".-.-." )) return 'H' ;
if(0==strcmp(morse, ".-." )) return 'I' ;
if(0==strcmp(morse, ".-.-.-" )) return 'J' ;
if(0==strcmp(morse, "-.-" )) return 'K' ;
if(0==strcmp(morse, ".-.-." )) return 'L' ;
if(0==strcmp(morse, "-.-" )) return 'M' ;
if(0==strcmp(morse, "-.-" )) return 'N' ;
if(0==strcmp(morse, "-.-.-" )) return 'O' ;
if(0==strcmp(morse, ".-.-.-" )) return 'P' ;
if(0==strcmp(morse, "-.-.-" )) return 'Q' ;
if(0==strcmp(morse, ".-.-" )) return 'R' ;
if(0==strcmp(morse, ".-.-" )) return 'S' ;
if(0==strcmp(morse, "-.-" )) return 'T' ;
if(0==strcmp(morse, ".-.-" )) return 'U' ;
if(0==strcmp(morse, ".-.-.-" )) return 'V' ;
if(0==strcmp(morse, "-.-.-" )) return 'W' ;
if(0==strcmp(morse, "-.-.-" )) return 'X' ;
if(0==strcmp(morse, "-.-.-" )) return 'Y' ;
if(0==strcmp(morse, "-.-.-" )) return 'Z' ;

if(0==strcmp(morse, "-----")) return '0' ;
if(0==strcmp(morse, ".-----")) return '1' ;
if(0==strcmp(morse, "..----")) return '2' ;
if(0==strcmp(morse, "...--")) return '3' ;
if(0==strcmp(morse, "....-")) return '4' ;
if(0==strcmp(morse, ".....")) return '5' ;
if(0==strcmp(morse, "-.....")) return '6' ;
if(0==strcmp(morse, "--....")) return '7' ;
if(0==strcmp(morse, "---...")) return '8' ;
if(0==strcmp(morse, "----. ")) return '9' ;

if(0==strcmp(morse, ".-.-" )) return ' ' ;
if(0==strcmp(morse, ".....")) return 8 ;

// anything else
return '?' ;
}

// ----- Team Detect -----
//

// state variables
int state = 0 ;
int start_time = 0 ;
char capture[16] ;
int c ;

// enumerated states
#define S_INIT 0
#define S_IDLE 1
#define S_IN_DIH 2
#define S_IN_DAH 3
#define S_IN_CHAR 4

// state transition helper words
void new_state(int n_state)
{
start_time = millis() ;
state = n_state ;
}

int elapsed()
{
return millis() - start_time ;
}

```

```

// utility to get current detect rate
int rate ()
{
  int value ;
  value = analogRead(2) ;
  return value ;
}

// utility to tell if the user is blowing
int is_blowing = 0 ;
#define BAND (5)
int blowing()
{
  int pressure ;
  int level ;

  pressure = analogRead(0) ;
  level = analogRead(1) ;
  if(is_blowing) level = level - BAND ;
  else          level = level + BAND ;
  is_blowing = pressure > level ;
  return is_blowing ;
}

// the finite-state machine
void detect()
{
  // check the transitions for the current state
  switch(state)
  {
    // at startup, clear the buffer and go to idle
    case S_INIT:
      c = 0 ;
      new_state(S_IDLE) ;
      break ;

    // while idle, look for the start of blowing
    case S_IDLE:
      if(blowing())
      {
        displayDih() ;
        new_state(S_IN_DIH) ;
      }
      break ;

    // while in a DIH, look for long enough to be a DAH
    // or the end of blowing
    case S_IN_DIH:
      if(!blowing())
      {
        // end of DIH, save in buffer
        capture[c] = '.' ;
        c++ ;
        displaySpace() ;
        //displayChar('.') ;
        new_state (S_IN_CHAR) ;
      }
      if(elapsed()>rate())
      {
        displayDah() ;
        new_state (S_IN_DAH) ;
      }
      break ;

    // while in a DAH, look for the end of blowing
    case S_IN_DAH:

```

```
    if(!blowing())
    {
        // end of DAH, save in buffer
        capture[c] = '-' ;
        c++ ;
        displaySpace() ;
        //displayChar('-') ;
        new_state(S_IN_CHAR) ;
    }
    break ;

// still in a char but not in DIH or DAH
// look for start of a new DIH
// or long enough to be the end of a character
case S_IN_CHAR:
    if(blowing())
    {
        displayDih() ;
        new_state(S_IN_DIH) ;
    }
    if(elapsed()>3*rate())
    {
        // null-terminate the string
        capture[c] = 0 ;
        // clear the LEDs
        displayClear() ;
        // display the decoded character
        displayChar(decode(capture)) ;
        // clear out the buffer for more
        c = 0 ;
        new_state(S_IDLE) ;
    }
    break ;
}
}

// Arduino/Wiring processes:

void setup()
{
    displayInit() ;
}

void loop ()
{
    detect() ;
}
```